

Comment: The algebraic continuity theorem uses the algebraic limit theorem and the definition of continuous:

Algebraic Continuity Theorem:

- Theorem
- (1) The sum of two continuous fns is continuous.
 - (2) " difference " " "
 - (3) " product " " "
 - (4) " quotient " " " as long as the denominator is nonzero.
 - (5) " composition " " "

As a result, linear fns are continuous,
polynomials " "
rational fns are continuous on their
domain
fns defined by convergent Taylor series
are continuous.

Two important facts

- ① The continuous image of a compact set is compact.
i.e. If $f: U \rightarrow V$ is continuous, with $U, V \subseteq \mathbb{C}$,
and if $S \subseteq U$ is a compact subset of $\mathbb{C}$, then
 $f(S)$ is compact. $[f(S) = \{f(z) : z \in S\}]$

[recall: compact $\Leftrightarrow$ closed & bounded.]

② The continuous image of a connected set is connected.
i.e. If $f: U \rightarrow V$ is continuous, with $U, V \subseteq \mathbb{C}$, and
if $T \subseteq U$ is a connected subset of $\mathbb{C}$, then
 $f(T)$ is connected.

Important Example: The stereographic projection.

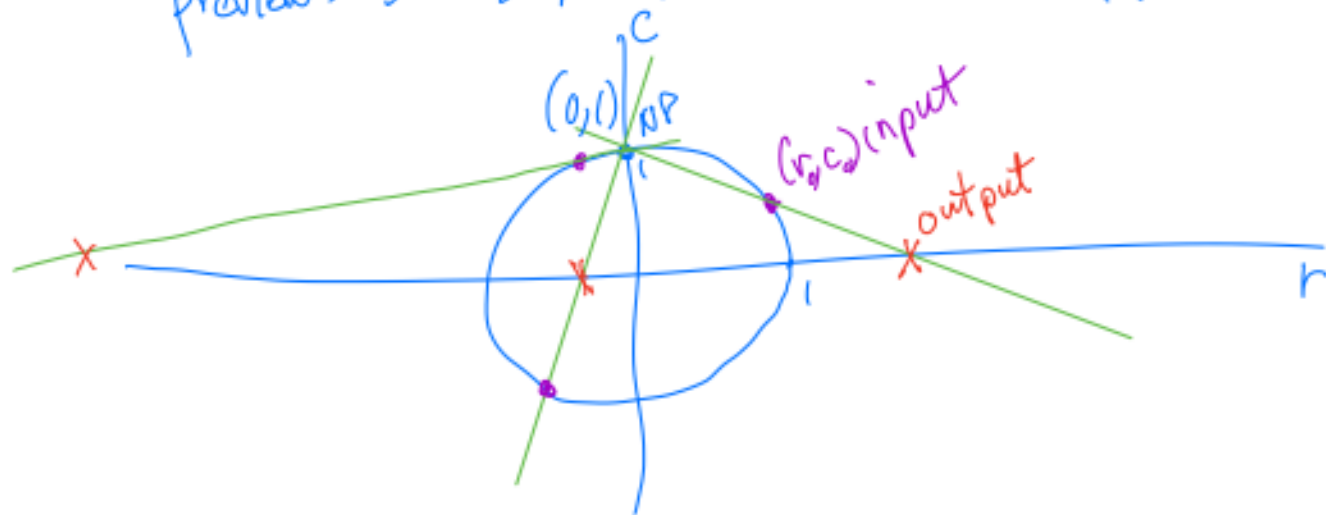
This is a function from the unit sphere in $\mathbb{R}^3$ whose image is $\mathbb{C}$ (really, $\mathbb{C} \cup \{\infty\}$),

It is a 1-1 and onto continuous map that is actually conformal — it preserves angles between curves.

$$\left[\text{unit sphere in } \mathbb{R}^3 = \{(a,b,c) : a^2+b^2+c^2=1\} \right]$$

(centered at $(0,0,0)$, radius 1.)

preview: stereographic projection on $\mathbb{R}^2 \rightarrow \mathbb{R}$



Given (r_0, c_0) on the unit circle $r^2 + c^2 = 1$, $(r_0, c_0) \neq (0, 1)$
 I will make the line connecting $(0, 1)$ and (r_0, c_0) , and
 my map will be $\phi(r_0, c_0) =$ point on the r axis
 where that line hits. $\phi: \underbrace{(\text{unit circle})}_{\text{circle}} \rightarrow \mathbb{R} \cup \{\infty\}$

Let's compute this map:

Slope of line $= \frac{c_0 - 1}{r_0}$, y -intercept $= 1$

line equation: $c = \left(\frac{c_0 - 1}{r_0}\right)r + 1$

where does it hit the r -axis?

$$c = 0 = \left(\frac{c_0 - 1}{r_0}\right)r + 1 \Rightarrow$$

$$\left(\frac{c_0 - 1}{r_0}\right)r = -1 \Rightarrow r = \frac{-r_0}{c_0 - 1}$$

$$\Rightarrow r = \frac{r_0}{1 - c_0}$$

Stereographic projection map:

$\phi(r_0, c_0) = \frac{r_0}{1 - c_0}$	$\text{if } (r_0, c_0) \neq (0, 1)$
	$\phi(0, 1) = \infty$

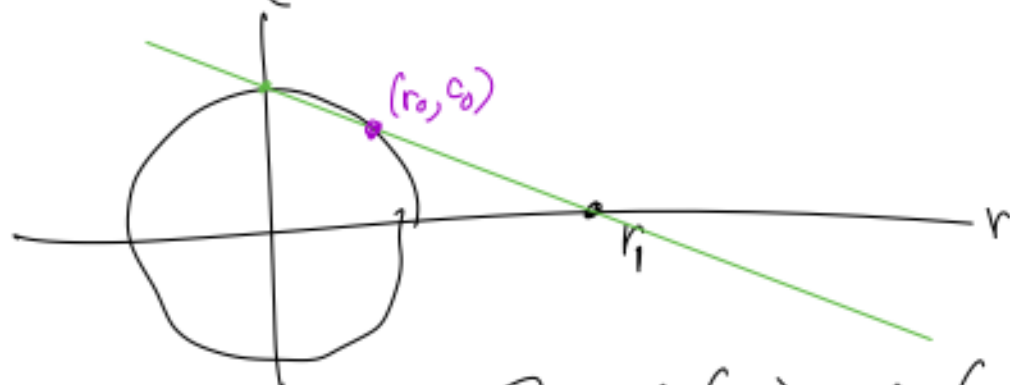
Notice: $\phi(r_0, 0) = r_0$

(Stereographic projection maps "equator" to itself.)

ϕ maps (lower part of circle) to $[-1, 1]$ on r -axis

ϕ maps (upper part of circle) to $(-\infty, -1) \cup (1, \infty]$.

(inverse map: Given r on the r -axis, what point (r_0, c_0) gets mapped to it?



eqn of line: Through $(0, 1)$ and $(r_1, 0)$.

$$\text{slope} = \frac{1}{-r_1} = -\frac{1}{r_1}.$$

$$y\text{-int} = 1$$

$$C = \left(-\frac{1}{r_1}\right)r + 1$$

$$r^2 + C^2 = 1$$

$$r^2 + \left(-\frac{r}{r_1} + 1\right)^2 = 1$$

$$r^2 + \frac{r^2}{r_1^2} + 1 - \frac{2r}{r_1} = 1$$

$$\left(1 + \frac{1}{r_1^2}\right)r^2 - \frac{2}{r_1}r = 0$$

$$r \left(\left(1 + \frac{1}{r_1^2}\right)r - \frac{2}{r_1} \right) = 0$$

$$r = 0 \text{ or } r = \frac{\frac{2}{r_1}}{1 + \frac{1}{r_1^2}} = \frac{2r_1}{r_1^2 + 1}$$

$$C = \left(-\frac{1}{r_1}\right)(r) + 1$$

$$C = -\frac{1}{r_1} \left(\frac{2r_1}{r_1^2+1}\right) + 1 = -\frac{2}{r_1^2+1} + 1$$

$$= \frac{-2}{r_1^2+1} + \frac{r_1^2+1}{r_1^2+1} = \frac{r_1^2-1}{r_1^2+1}$$

$$\phi^{-1}(r_0, c_0) = \left(\frac{2r_1}{r_1^2+1}, \frac{r_1^2-1}{r_1^2+1}\right)$$

$$\phi^{-1}(r_1) = \left(\frac{2r_1^{r_0}}{r_1^2+1}, \frac{r_1^2-1}{r_1^2+1}\right) \leftarrow \begin{matrix} \text{we} \\ \text{can check} \\ r_0^2 + c_0^2 = 1 \end{matrix}$$

$$\phi^{-1}(\infty) = (0, 1)$$

Summary:

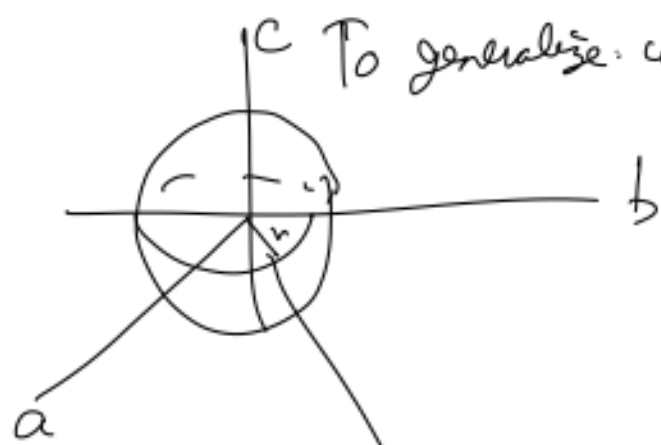
$$\phi(r_0, c_0) = \frac{r_0}{1-c_0} = r_1$$

$$\phi(0, 1) = \infty$$

$$\phi^{-1}(r_1) = \left(\frac{2r_1}{r_1^2+1}, \frac{r_1^2-1}{r_1^2+1}\right) \quad \phi^{-1}(\infty) = (0, 1)$$

Comment: We could generalize to
a map $\phi: S^n \rightarrow \mathbb{R}^n \cup \{\infty\}$

We'll stick to the case $n=2$ $\phi: S^2 \rightarrow \mathbb{R}^2 \cup \{\infty\}$
 $= \mathbb{C} \cup \{\infty\}$



To generalize, we rotate around the c axis.

Think of r as the radius.

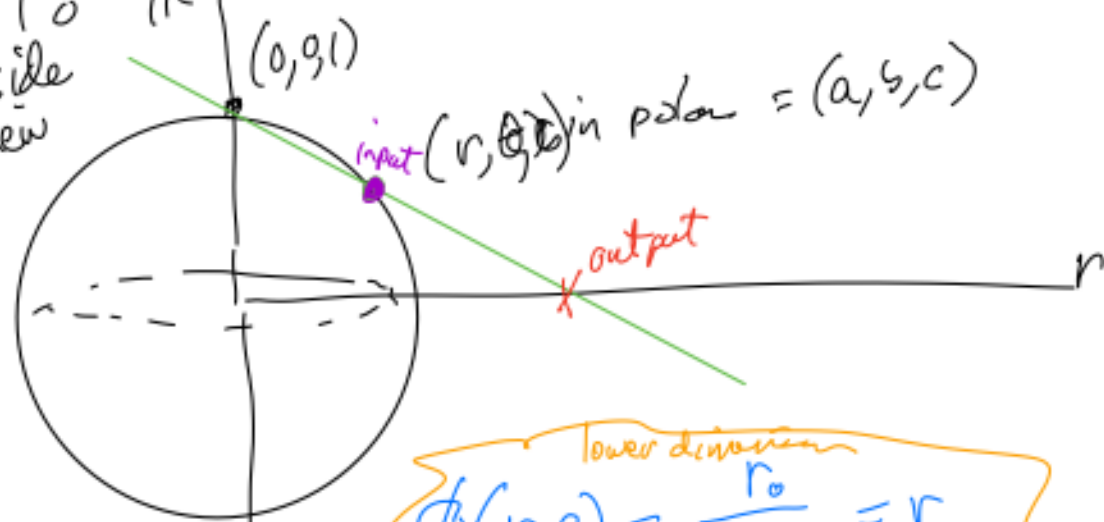
We will construct a map from

$$S^2 \subseteq \mathbb{R}^3$$

$$S^2 = \{(a, b, c) : a^2 + b^2 + c^2 = 1\}$$

$$\mathbb{R}^2 = \mathbb{C} = \{(x + iy) = (x, y) : x, y \in \mathbb{R}\}.$$

To
Side
view



The angular
coordinate θ
in the (a, b) plane
does not change.

lower dimension

$$\phi(b, c) = \frac{r_0}{1 - c_0} = r_1$$

$$\phi^{-1}(r_1) = \left(\frac{2r_1}{r_1^2 + 1}, \frac{r_1^2 - 1}{r_1^2 + 1} \right)$$

$$\phi(a_0, b_0, c_0) = (x, y)$$

where $x = r_1 \cos \theta$
 $y = r_1 \sin \theta$

$$\begin{aligned} c_0 &= c_0 \\ a_0 &= r_0 \cos \theta \\ b_0 &= r_0 \sin \theta \end{aligned}$$

$$\frac{\overbrace{r_0 \cos \theta}^{a_0}}{1 - c_0} = r_1 \cos \theta = x$$

$$\frac{\overbrace{r_0 \sin \theta}^{b_0}}{1 - c_0} = r_1 \sin \theta = y$$

Formula $\phi: S^2 \rightarrow \mathbb{C} \cup \{\infty\}$

$$\begin{aligned} \phi(a_0, b_0, c_0) &= \left(\frac{a_0}{1 - c_0}, \frac{b_0}{1 - c_0} \right) \\ &= \left(\frac{a_0}{1 - c_0} + i \frac{b_0}{1 - c_0} \right) \end{aligned}$$

Inverse

~~$$\phi^{-1}(r_1) = \left(\frac{2r_1}{r_1^2 + 1}, \frac{r_1^2 - 1}{r_1^2 + 1} \right)$$~~

$$\phi^{-1}(\underbrace{r_1 \cos \theta}_x, \underbrace{r_1 \sin \theta}_y) = \left(\frac{2r_1 \cos \theta}{r_1^2 + 1}, \frac{2r_1 \sin \theta}{r_1^2 + 1}, \frac{r_1^2 - 1}{r_1^2 + 1} \right)$$

$$\phi^{-1}(x, y) = \left(\frac{2x}{x^2+y^2+1}, \frac{2y}{x^2+y^2+1}, \frac{x^2+y^2-1}{x^2+y^2+1} \right)$$

$$r_1^2 = x^2 + y^2.$$

(Stereographic projection maps equator to itself.)
 ϕ maps (lower part of sphere) to the unit disk in $\mathbb{C}$:-
 ϕ maps (upper part of sphere) to the complement of the unit disk in $\mathbb{C}$.

Note: $S^2 \cap \mathbb{C} = \text{unit circle in } \mathbb{C}$



Properties: Note: every plane intersects S^2 in a circle.

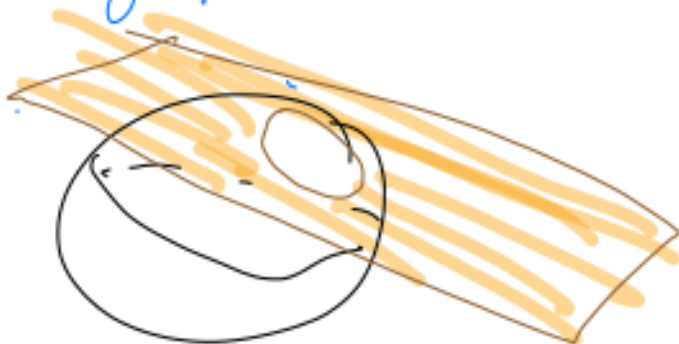
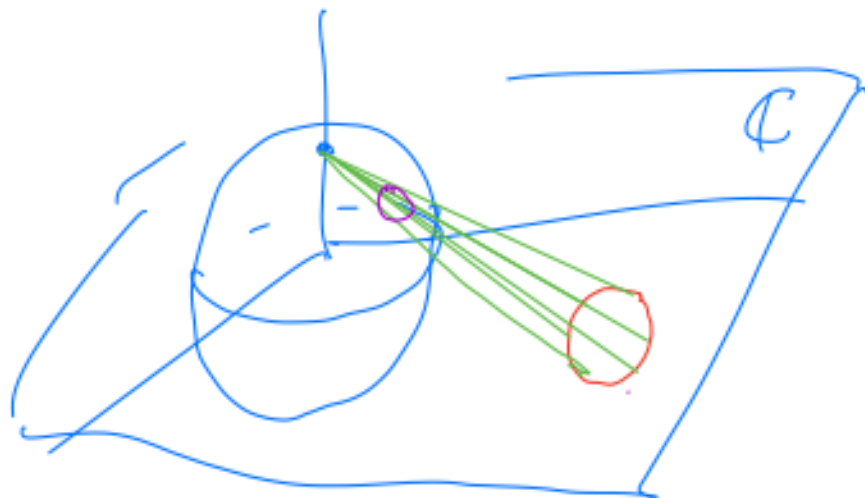
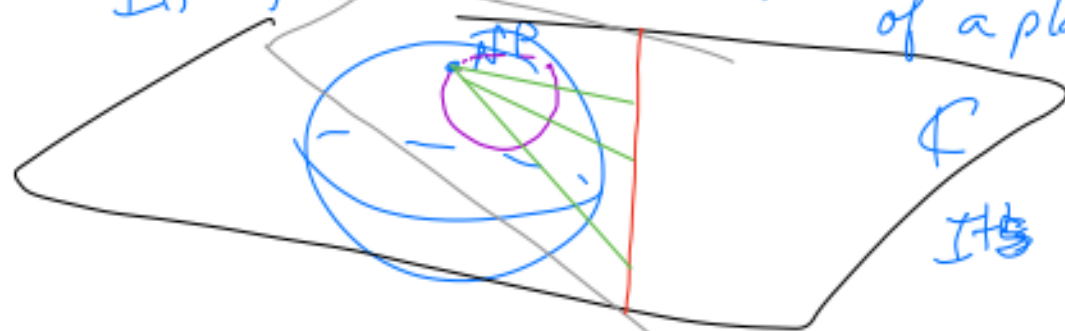


Image of every circle in S^2
under the stereographic projection
map is either a circle or a line
(you can prove this.)



If the circle is on S^2 , it is the intersection
of a plane through
the north
pole.



Its image

under ϕ is the intersection of that
plane with $\mathbb{C}$. Since it is the intersection
of two planes, it is a line.